

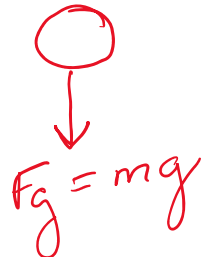
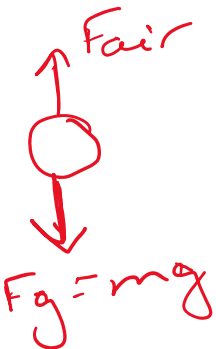
# Lesson Video: Physics 12 – Analysis of Systems of Masses - free body diagrams and Newton's Second Law

Lesson video: <https://www.loom.com/share/2803644ca7fa4b22ae0978fc41e533f4>

Refer to the example situations depicted below. For each situation, you will:

- i) Draw and label a free body diagram
  - ii) Develop the equation for the acceleration of the mass or system of masses.
- Analyze the example situations one at a time, in order.

*Dynamics*

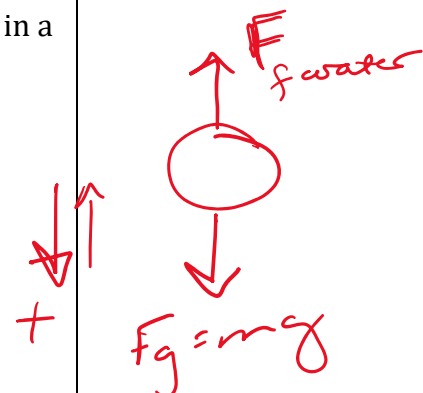

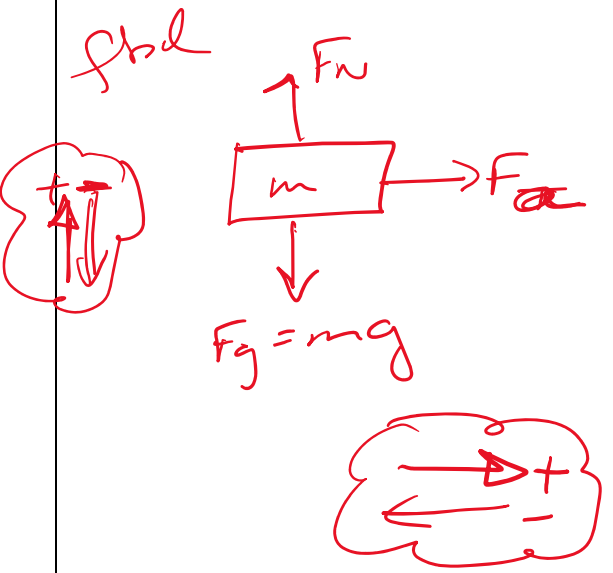
	Example Situation	fbd (free body diagram) -	System Analysis using Newton's 2 <sup>nd</sup> Law
1	Object in free fall (no friction or air resistance)		<p>Equation for acceleration</p> $\Sigma F = ma = \dots F_g \dots$ $m\vec{a} = mg$ $\vec{a} = g$
2	Object in free fall, but air resistance is <b>not</b> equal to zero		<p>Equation for acceleration</p> $\Sigma F = ma = mg - F_{air}$ $\vec{a} = \frac{mg - F_{air}}{m}$ <p>Condition for equilibrium (acceleration = zero, speed = "terminal velocity")</p> $m\vec{a} = mg - F_{air}$ $F_{air} = mg$

*terminal speed = max const speed*

*refer to fbd*

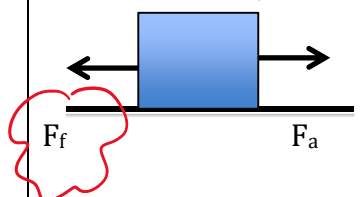
$\Sigma F = 0$   
 if  $\Sigma F = 0$   
 then  $\vec{a} = 0$

*F\_{air} = mg - ma*

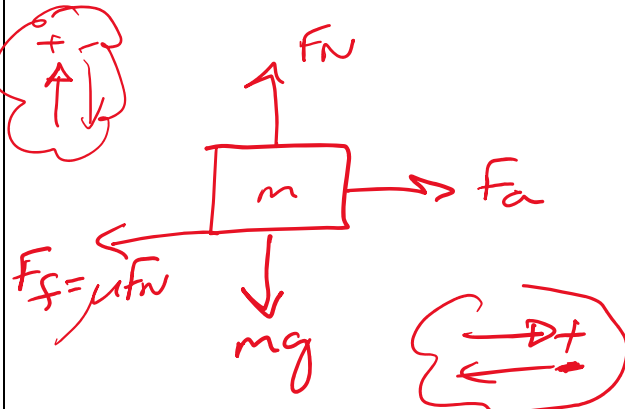
3	<p>A stone falling through water (e.g. it has been dropped in a lake)</p>		<p>Equation for acceleration</p> $\Sigma F = m\vec{a} = mg - F_{f\text{water}}$ <div style="border: 1px solid red; padding: 5px; width: fit-content; margin: 5px auto;"> <math display="block">\vec{a} = \frac{mg - F_{f\text{water}}}{m}</math> </div> <p>Condition for equilibrium</p> $0 = mg - F_{f\text{water}}$ <div style="border: 1px solid red; padding: 5px; width: fit-content; margin: 5px auto;"> <math display="block">F_{f\text{water}} = mg</math> </div>
4	<p>Mass = m Applied Force = <math>F_a</math> to the right No friction: <math>F_f = 0\text{N}</math></p>  <p><del>not</del> not an fbsd</p>	<p>fbsd</p> 	<p>Equation for acceleration</p> $\Sigma F_y = ma_y = F_N - mg$ $a_y = 0 \quad 0 = F_N - mg$ $\therefore F_N = mg$ $\Sigma F_x = ma_x = F_a$ <div style="border: 1px solid red; padding: 5px; width: fit-content; margin: 5px auto;"> <math display="block">a_x = \frac{F_a}{m}</math> </div>

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Mass =  $m$   
 Applied Force =  $F_a$  to the right  
 Friction:  $F_f \neq 0N$ , to the left



$F_f$   $F_a$



$F_N$   
 $F_a$   
 $mg$   
 $F_f = \mu F_N$

Equation for acceleration

Refer to # 4  $\rightarrow F_N = mg$  for proof.

$$\sum F_x = m a_x = F_a - F_f$$

$$m a_x = F_a - \mu F_N$$

$$m a_x = F_a - \mu m g$$

$$a_x = \frac{F_a - \mu m g}{m}$$

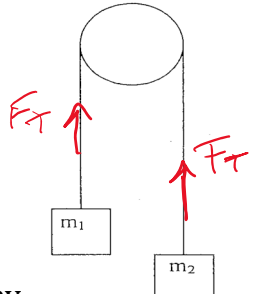
Condition for equilibrium

$$\sum F = 0 \therefore a = 0$$

$$\sum F_x = m a_x = F_a - \mu m g$$

$$\therefore F_a = \mu m g$$

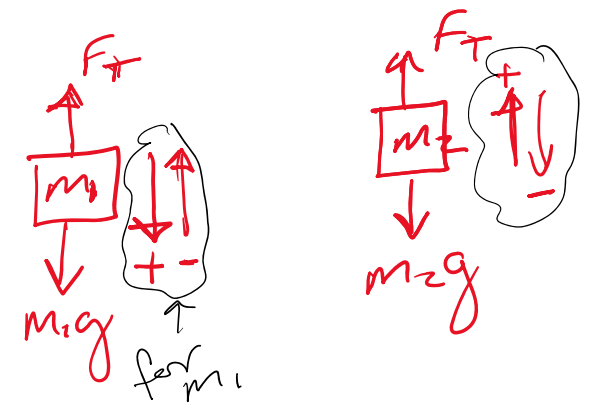
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Pulley supporting two hanging masses

$F_T = F_T$   
 magnitude of  $F_T$  is equal everywhere

fbd for each mass



$F_T$   
 $m_1 g$   
 $F_T$   
 $m_2 g$

Equation for acceleration

$$\sum F_1 = m_1 a = m_1 g - F_T$$

$$\sum F_2 = m_2 a = F_T - m_2 g$$

$$m_1 a + m_2 a = m_1 g - F_T + F_T - m_2 g$$

$$a(m_1 + m_2) = g(m_1 - m_2)$$

$$a = \frac{g(m_1 - m_2)}{m_1 + m_2}$$

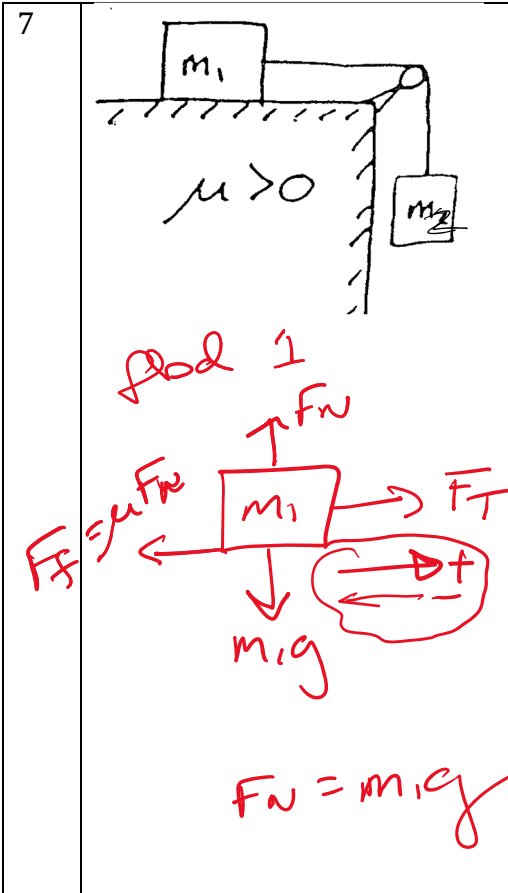
Equation for tension of the connecting cord

$$F_T = m_1 g - m_1 a$$

$$F_T = m_1 (g - a)$$

refer to answer key

Sign convention must be consistent, with respect direction of  $a$  if  $m_1$  is accelerating down then  $m_2$  is up.



Equation for acceleration

$$\sum F_1 = m_1 a = F_T - \mu m_1 g$$

$$\sum F_2 = m_2 a = m_2 g - F_T$$

$$m_1 a + m_2 a = m_2 g - \mu m_1 g$$

$$a = \frac{g(m_2 - \mu m_1)}{m_1 + m_2}$$

Equation for tension of the connecting cord

$$F_T = m_2(g - a)$$

$$F_T = m_1 a + \mu m_1 g$$

$$F_T = m_1(a + \mu g)$$

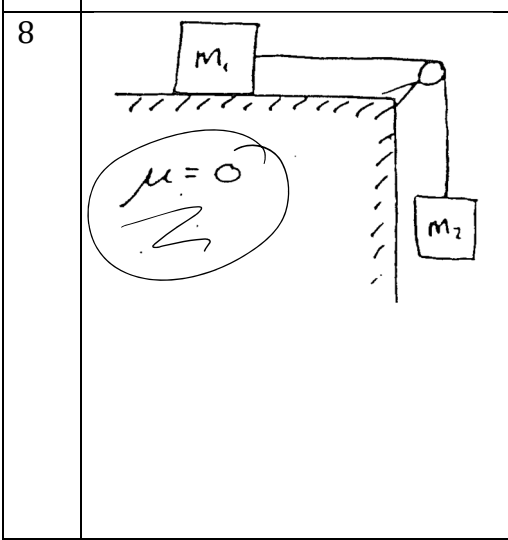
Condition for equilibrium  $\vec{a} = 0$

$$0 = \frac{g(m_2 - \mu m_1)}{m_1 + m_2}$$

$$m_2 - \mu m_1 = 0$$

$$m_2 = \mu m_1$$

$$\mu = \frac{m_2}{m_1}$$



Equation for acceleration

$$a = \frac{m_2 g}{m_1 + m_2}$$

Equation for tension of the connecting cord

$$F_T = m_2(g - a)$$

$$F_T = m_1 a$$

Equation for acceleration

$$a = \frac{m_2 g}{m_1 + m_2}$$

Equation for tension of the connecting cord

$$F_T = m_2(g - a)$$

$$F_T = m_1 a$$

Equation for acceleration

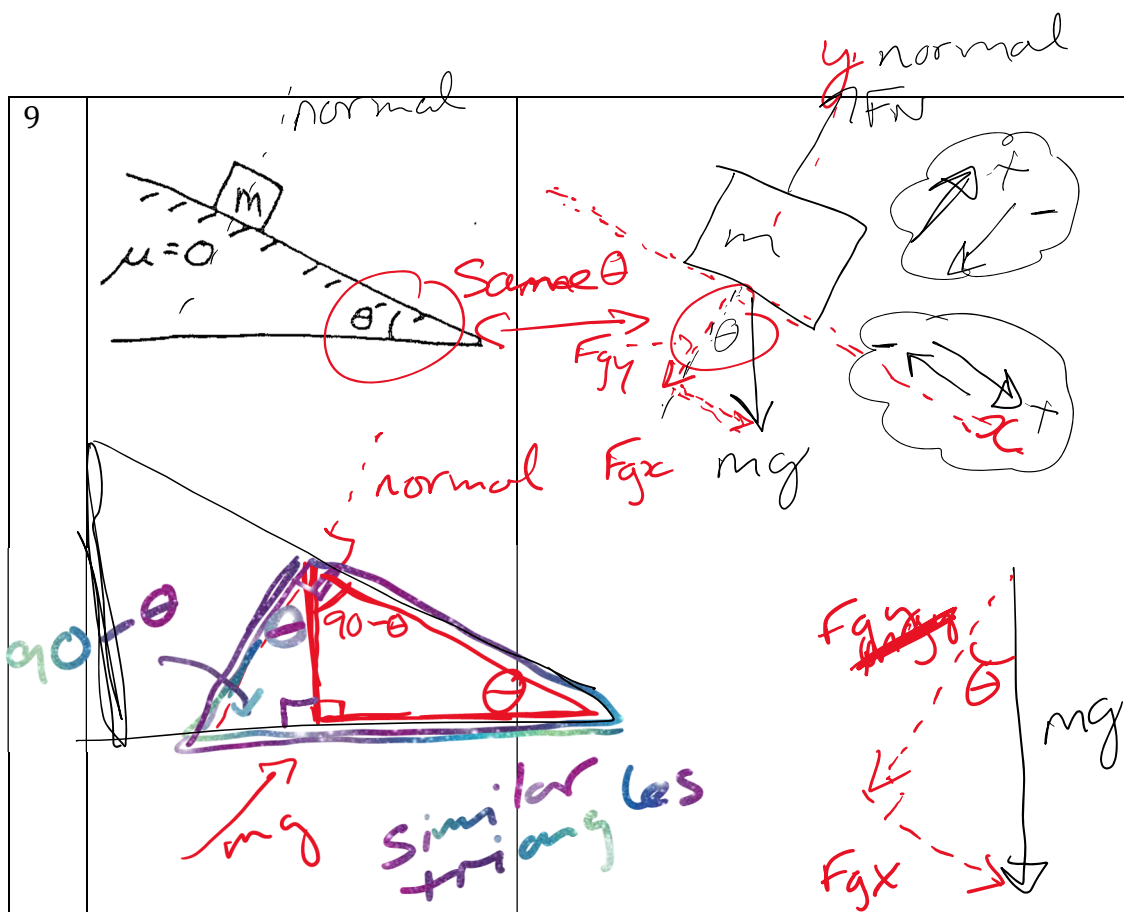
$$a = \frac{m_2 g}{m_1 + m_2}$$

Equation for tension of the connecting cord

$$F_T = m_2(g - a)$$

$$F_T = m_1 a$$

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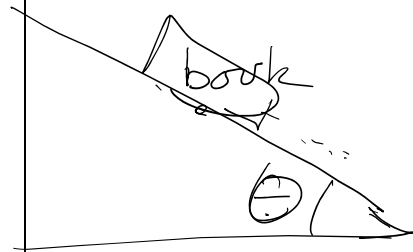
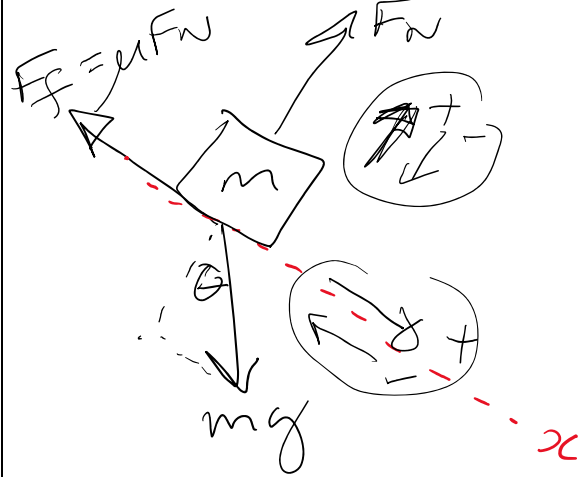
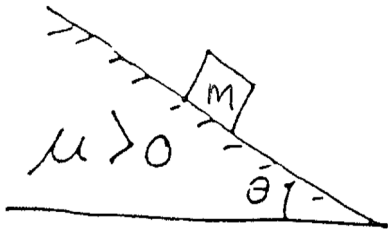
Equation for acceleration

$$\sum F_y = ma_y = F_N - mg \cos \theta$$

$$\underline{a_y = 0} \quad \underline{F_N = mg \cos \theta}$$

$$\sum F_x = ma_x = mg \sin \theta$$

$$a \quad \boxed{\vec{a}_x = g \sin \theta}$$



Equation for acceleration

$$F_N = mg \cos \theta \quad (\text{refer to } \# 9 \text{ for proof})$$

$$\sum F_x = \text{max} = mg \sin \theta - \mu mg \cos \theta$$

$$\vec{a} = g (\sin \theta - \mu \cos \theta)$$

Condition for equilibrium  $\vec{a} = 0$

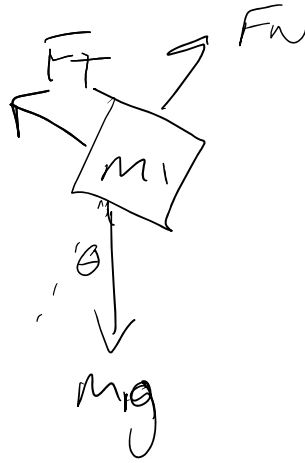
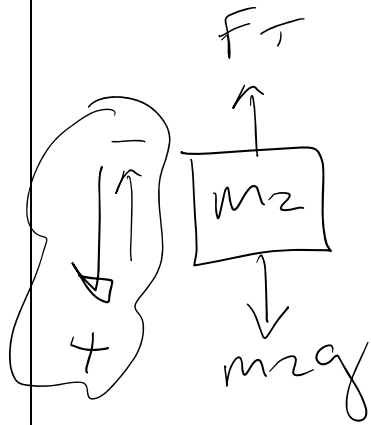
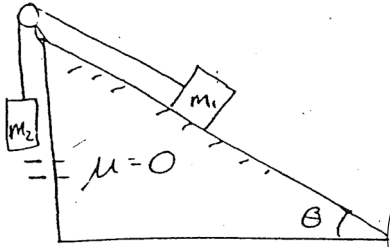
$$0 = g (\sin \theta - \mu \cos \theta)$$

$$0 = \sin \theta - \mu \cos \theta$$

$$\mu = \frac{\sin \theta}{\cos \theta} = \tan \theta$$

$$\mu = \tan \theta$$

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Equation for acceleration

$$\sum F_1 = m_1 a = F_T - m_1 g \sin \theta$$

$$\sum F_2 = m_2 a = m_2 g - F_T$$

$$(m_1 + m_2) a = m_2 g - m_1 g \sin \theta$$

$$a = \frac{g(m_2 - m_1 \sin \theta)}{m_1 + m_2}$$

Equation for tension of the connecting cord

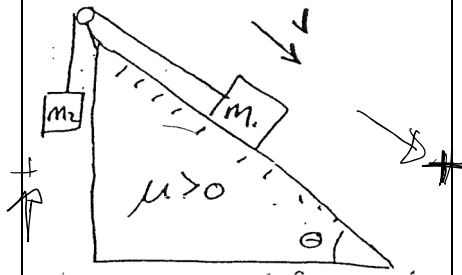
$$F_T = m_2 (g - a)$$

$$F_T = m_1 (a + g \sin \theta)$$

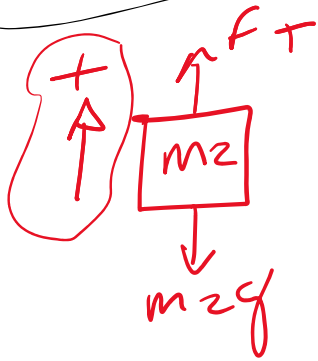
Condition for equilibrium

$$a = 0 \quad \text{so} \quad m_2 - m_1 \sin \theta = 0$$

$$\text{so} \quad m_2 = m_1 \sin \theta$$

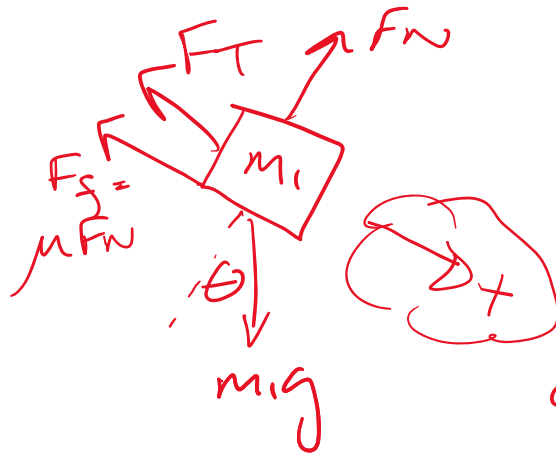


The system is sliding to the right ( $m_1$  is sliding down the slope, and  $m_2$  is moving upward)



if  $m_1 g \sin \theta > m_2 g$   
then  $F_f$  is to left  
(up slope)

if  $m_1 g \sin \theta < m_2 g$   
then  $F_f$  is to the right  
(down slope)



$$F_N = m_1 g \cos \theta$$

Equation for acceleration

$$\sum F_2 = m_2 a = F_T - m_2 g$$

$$\sum F_1 = m_1 a = m_1 g \sin \theta - F_T - \mu m_1 g \cos \theta$$

$$a(m_1 + m_2) = m_1 g \sin \theta - m_2 g - \mu m_1 g \cos \theta$$

$$a = \frac{m_1 g \sin \theta - m_2 g - \mu m_1 g \cos \theta}{m_1 + m_2}$$

Equation for tension of the connecting cord

$$F_T = m_2 (a + g)$$

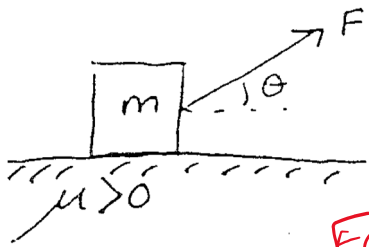
$$F_T = m_1 g \sin \theta - \mu m_1 g \cos \theta - m_2 g$$

Condition for equilibrium  $a = 0$

$$0 = m_1 g \sin \theta - m_2 g - \mu m_1 g \cos \theta$$

$$m_1 \sin \theta = m_2 + \mu m_1 \cos \theta$$

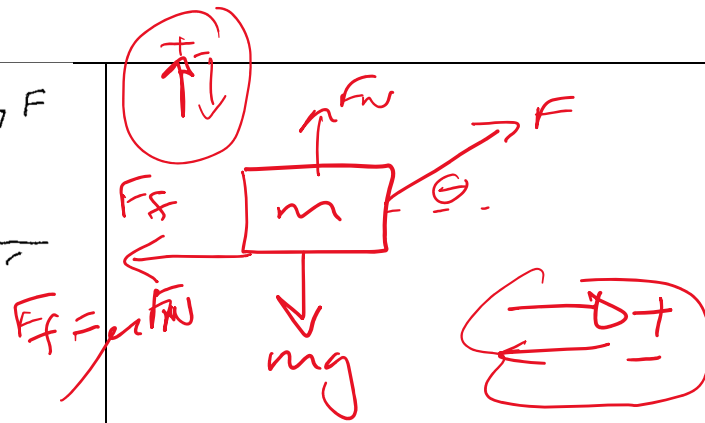




$$a_y = 0$$

$$\sum F_y = 0 = F_n + F \sin \theta - mg$$

$$F_n = mg - F \sin \theta$$



Equation for acceleration

$$\sum F_x = ma_x = F \cos \theta - F_f$$

$$ma_x = F \cos \theta - \mu F_n$$

$$ma_x = F \cos \theta - \mu (mg - F \sin \theta)$$

$$a_x = \frac{F \cos \theta - \mu mg + \mu F \sin \theta}{m}$$

Condition for equilibrium

$$0 = F \cos \theta - \mu mg + \mu F \sin \theta$$